PATENT COOPERATION TREATY

TRANSLATION From the INTERNATIONAL SEARCHING AUTHORITY WRITTEN OPINION OF THE INTERNATIONAL SEARCHING AUTHORITY (PCT Rule 43bis.1) Date of mailing (day/month/year) Applicant's or agent's file reference FOR FURTHER ACTION PCT05234 See paragraph 2 below International application No. International filing date (day/month/year) Priority date (day/month/year) PCT/JP2005/021879 29.11.2005 16.12.2004 International Patent Classification (IPC) or both national classification and IPC Applicant HONDA MOTOR CO., LTD. This opinion contains indications relating to the following items: Box No. I Basis of the opinion Box No. II Priority Box No. III Non-establishment of opinion with regard to novelty, inventive step and industrial applicability Box No. IV Lack of unity of invention Box No. V Reasoned statement under Rule 43bis.1(a)(i) with regard to novelty, inventive step or industrial applicability; citations and explanations supporting such statement Box No. VI Certain documents cited Box No. VII Certain defects in the international application Box No. VIII Certain observations on the international application 2 **FURTHER ACTION** If a demand for international preliminary examination is made, this opinion will be considered to be a written opinion of the International Preliminary Examining Authority ("IPEA") except that this does not apply where the applicant chooses an Authority other than this one to be the IPEA and the chosen IPEA has notified the International Bureau under Rule 66.1bis(b) that written opinions of this International Searching Authority will not be so considered. If this opinion is, as provided above, considered to be a written opinion of the IPEA, the applicant is invited to submit to the IPEA a written reply together, where appropriate, with amendments, before the expiration of 3 months from the date of mailing of Form PCT/ISA/220 or before the expiration of 22 months from the priority date, whichever expires later. For further options, see Form PCT/ISA/220. For further details, see notes to Form PCT/ISA/220. Name and mailing address of the ISA/JP Date of completion of this opinion Authorized officer Facsimile No. Telephone No.

International application No.

PCT/JP2005/021879

Вох	No. I	Basis of this opinion				
1.	With	regard to the language, this opinion has been established on the basis of:				
	\boxtimes	the international application in the language in which it was filed				
		the translation of the international application into, which is the language of a				
		translation furnished for the purposes of international search (Rule 12.3(a) and 23.1(b)).				
2. With regard to any nucleotide and/or amino acid sequence disclosed in the international application and necessary to invention, this opinion has been established on the basis of:						
	a.	type of material				
		a sequence listing				
		table(s) related to the sequence listing				
	b.	format of material				
		on paper				
		in electronic form				
	С.					
		contained in the international application as filed				
		filed together with the international application in electronic form				
		furnished subsequently to this Authority for the purposes of search				
3.		In addition, in the case that more than one version or copy of a sequence listing and/or table(s) relating thereto has been filed or furnished, the required statements that the information in the subsequent or additional copies is identical to that in the application as filed or does not go beyond the application as filed, as appropriate, were furnished.				
4.	Addi	tional comments:				

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Box			CHING AUTHORITY	PCT/JP2005/0218	79		
				inventive step or industrial applicability;			
1.	citations and explanations supporting such statement Statement						
	Novelty (N)	Claims	1-14		YE!		
					NO		
	Instanting stars (IC)						
	Inventive step (IS)	Claims					
	Industrial applicability (IA)	Claims	1-14		YES		
2.	Citations and explanations:						
			A (Honda Motor Co., Ltd.) 547567 A1 & WO 2004/017	, 11 March 2004, full text; all 890 A1			
	Document 2: JP 2004-drawings			o.), 17 June 2004, full text; all			
	Document 3: JP 2004-105261 A (Matsushita Electric Industrial Co., Ltd.), 08 April 2004, full text; all drawings, (Family: none)						
	Document 4: JP 2003-drawings	-089083 & EP 14	A (Honda Motor Co., Ltd.) 10780 A1 & WO 2003/002	, 25 March 2003, full text; all 2054 A1			
			A (Honda Motor Co., Ltd.) 10780 A1 & WO 2003/002	, 18 March 2003, full text; all 2054 A1			
			A (Honda Motor Co., Ltd.) 442703 A1 & WO 2003/03	, 22 April 2003, full text; all 2832 A1			

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Box No. VIII Certain observations on the international application The following observations on the clarity of the claims, description, and drawings or on the question whether the claims are fully supported by the description, are made: In claims 1, 3, 9, 13, and 14 it is described that "a value of factor γ is set in accordance with a factor function γ (f, y) with an external force f and a motion variable y as variables," but the meaning is unclear as to what kind of function. Claim 2 describes "a base function $F(x, \alpha)$ with an electric potential x and a coefficient α as variables," but the meaning is unclear as to what kind of function.

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Supplemental Box

In case the space in any of the preceding boxes is not sufficient.

Continuation of: Box V

Claims 1 to 5

The inventions of claims 1 to 5 do not appear to involve an inventive step based on documents 1 to 3 cited in the ISR. Documents 1 to 3 describe an external force control method having a myopotential measuring step of measuring a myopotential x produced by a body of an animal, an external force setting step of setting a value of an external force f to be effected on an animal via an outfit in accordance with an external force function f(x)- with the myopotential x as a variable based on a measurement value of the myopotential x, and a motion variable measuring step of measuring a motion variable y that varies in accordance with motion of an animal in a state which the external force f is being effected via the outfit.

Carrying out feedback control is a widely known technical matter.

Claims 6 and 7

The inventions of claims 6 and 7 do not appear to involve an inventive step based on documents 1 to 5 cited in the ISR. Documents 4 to 5 disclose an external force control method in which measurements of resultant force F are provided.

Claims 8 to 12

The inventions of claims 8 to 12 do not appear to involve an inventive step based on claims 1 to 6 cited in the ISR. Document 6 discloses a step of determining a condition of motion in which a condition of motion of an animal is determined in accordance with a predetermined responsive relationship between a base motion variable and a motion condition of an animal.

Claim 13

Documents 1 to 3 describe an external force control system in which an external force effected on an animal is controlled via an outfit fitted on the animal moving in accordance with muscle fiber activity, having myopotential measuring means of measuring a myopotential x produced by a body of an animal, external force setting means of setting a value of an external force f to be effected on an animal via an outfit in accordance with an external force function f(x)- with the myopotential x as a variable based on a measurement value of the myopotential x by myopotential measuring means, and motion variable measuring meeans of measuring a motion variable y that varies in accordance with motion of an animal in a state in which an external force is being effected via the outfit.

Feedback control systems are widely known technical matters.

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Supplemental Box

Continuation of: Box V

Claim 14

Documents 1 to 3 disclose an external force control program provided in a computer having a function controlling an external force effected on an animal via an outfit fitted on the animal moving in accordance with muscle fiber activity, having a myopotential measuring function of measuring a myopotential x produced by a body of an animal, an external force setting function of setting a value of an external force f to be effected on an animal via an outfit in accordance with an external force function f(x)- with the myopotential x as a variable based on a measurement value of the myopotential x, and a motion variable measuring function of measuring a motion variable y that varies in accordance with motion of an animal in a state in which an external force is being effected via the outfit.

Feedback control programs are widely known technical items.